

Abstract

The invention relates to a method for assisting the driver of a vehicle (10) during a driving maneuver such as, for example, a parking or positioning maneuver. In such a case, a reference trajectory (16) along which the vehicle (10) is to be moved is determined. A steering wheel position which is to be set and which steers the vehicle along the reference trajectory (16) is indicated to the driver during the driving maneuver. A steering angle deviation between the actual steering angle which is actually set by the driver and the setpoint steering angle which corresponds to the requested steering wheel position is corrected independently of the driver.

Fig. 1